

Brushless DC-Servomotors

with integrated Speed Controller

4 Pole Technology

73 mNm

For combination with
Gearheads:
32A, 32ALN, 32/3, 32/3 S, 38/1, 38/1S, 38/2, 38/2 S

Series 3268 ... BX4 SC

	3268 G		024 BX4	SC
1 Nominal voltage	U_N		24	Volt
2 Terminal resistance, phase-phase	R		1,45	Ω
3 Output power ¹⁾	$P_{2 \text{ max.}}$		32,7	W
4 Efficiency	$\eta_{\text{ max.}}$		79,5	%
5 No-load speed	n_0		5 500	rpm
6 No-load current	I_0		0,215	A
7 Stall torque	M_H		137	mNm
8 Friction torque, static	C_0		1,7	mNm
9 Friction torque, dynamic	C_v		$1,3 \cdot 10^{-3}$	mNm/rpm
10 Speed constant	k_n		220	rpm/V
11 Back-EMF constant	k_E		4,555	mV/rpm
12 Torque constant	k_M		43,5	mNm/A
13 Current constant	k_I		0,0230	A/mNm
14 Slope of n-M curve	$\Delta n / \Delta M$		7,3	rpm/mNm
15 Terminal inductance, phase-phase	L		110	μH
16 Mechanical time constant	τ_m		4,6	ms
17 Rotor inertia	J		60	gcm^2
18 Angular acceleration	$\alpha_{\text{ max.}}$		23	$\cdot 10^3 \text{ rad/s}^2$
19 Thermal resistance	$R_{\text{th } 1} / R_{\text{th } 2}$	1,9 / 9,6		K/W
20 Thermal time constant	τ_{w1} / τ_{w2}	17 / 1 060		s
21 Operating temperature range		- 40 ... + 100		$^{\circ}\text{C}$
22 Shaft bearings		ball bearings, preloaded		
23 Shaft load max.:				
– radial at 3 000 rpm (4,5 mm from mounting flange)		50		N
– axial at 3 000 rpm		5		N
– axial at standstill		50		N
24 Shaft play:				
– radial	\leq	0,015		mm
– axial	$=$	0		mm
25 Housing material		stainless steel		
26 Weight		305		g
27 Direction of rotation		electronically reversible		
28 Number of pole pairs		2		
Recommended values - mathematically independent of each other				
29 Speed up to	$n_{\text{e max.}}$		7 000	rpm
30 Torque up to ^{1) 2)}	$M_{\text{e max.}}$		47 / 73	mNm
31 Current up to ^{1) 2)}	$I_{\text{e max.}}$		1,41 / 2,00	A

¹⁾ at $U_{\text{soll}} = 10\text{V}$

²⁾ thermal resistance $R_{\text{th } 2}$ not reduced / thermal resistance $R_{\text{th } 2}$ by 55% reduced

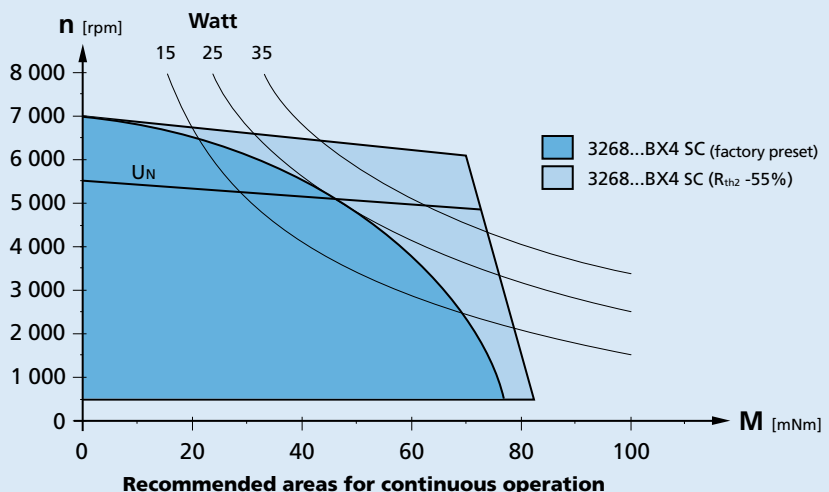
Note:

The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22°C.

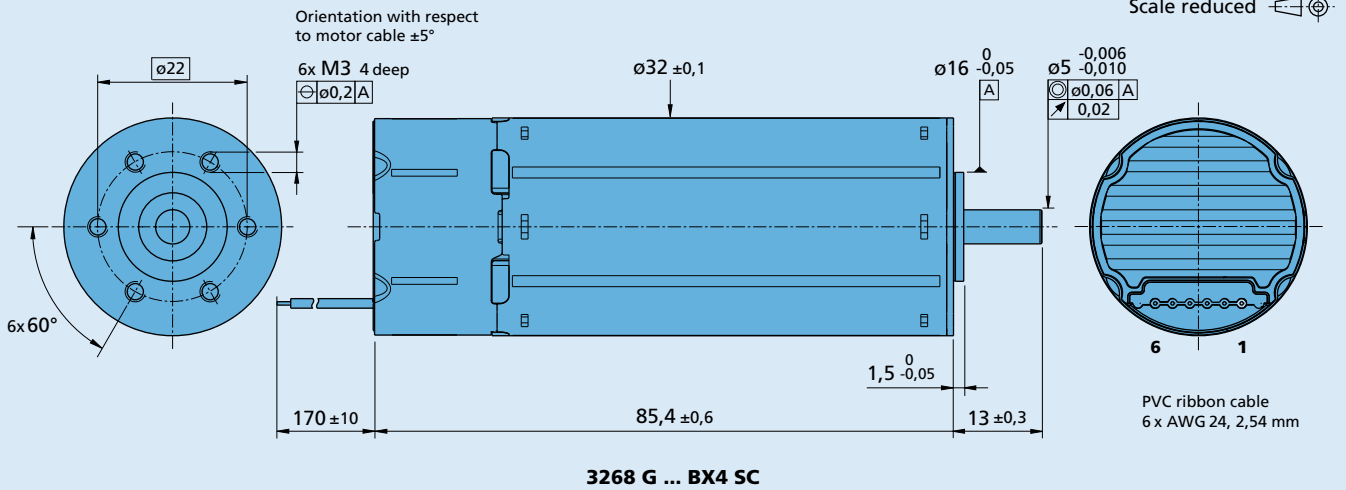
The diagram shows the motor in a completely insulated as well as thermally coupled condition ($R_{\text{th } 2} \geq 55\%$ reduced).

The motor is factory pre-configured to a continuous current for the thermally insulated condition. The controller must be reconfigured with the easy to use Motion Manager Software for use at higher continuous current.

The nominal voltage (U_N) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.



Dimensional drawing



Speed Controller		024 BX4	SC
Power supply electronic	U_p	6,5 ... 30	V DC
Power supply motor	U_{mot}	6,5 ... 30	V DC
PWM switching frequency	f_{PWM}	96	kHz
Efficiency	η	95	%
Max. continuous output current ¹⁾	I_{dauer}	2	A
Max. peak output current	I_{max}	4	A
Total standby current at U_N	I_{el}	10	mA
Speed range:			
– standard » Hall sensors (digital)		400 ... 50 000 ²⁾	rpm
– optional » Hall sensors (analog)		50 ... 50 00 ²⁾	rpm
Scanning range		500	μ s

¹⁾ at 22°C ambient temperature and max. 60°C motor temperature at the nominal voltage of motor and electronics

²⁾ speed is dependent on the motor operating voltage

Connection 1 "U_P":	power supply electronic	U_p	
Connection 2 "U_{mot}":	power supply electronic coil	U_{mot}	
Connection 3 "GND":	ground	ground	
Connection 4 "U_{nsoll}":			
– analog input	input voltage	$U_{in} = 0 \dots 10 \text{ V} \mid > 10 \text{ V} \dots U_p$ » set speed value not defined	
	input resistance	$R_{in} \geq 8,9 \text{ k}\Omega$	
	set speed value	per 1 V, 1 000	rpm
		$U_{in} < 0,15 \text{ V}$ » motor stops	
		$U_{in} > 0,3 \text{ V}$ » motor starts	
Connection 5 "DIR":			
– digital input	direction of rotation	to ground or level < 0,5V » counterclockwise	
		open or level > 3V » clockwise	
	input resistance	$R_{in} \geq 10 \text{ k}\Omega$	
Connection 6 "FG":			
– digital output	frequency output	max. U_p ; $I_{max} = 15 \text{ mA}$; open collector with 22 k Ω pull-up resistor	
		6 lines per revolution	

Features

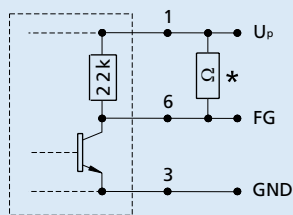
In this variant, the brushless DC servomotors have an integrated Speed Controller. The motor is commutated using Hall sensors integrated into the motor. Speed control is via a PI regulator.

The Speed Controller has a current limiting device which limits the maximum motor current if the thermal load is too high. Twice the continuous current is possible over a short time.

Using the "FAULHABER Motion Manager" software, the customer can modify the Speed Controller to special conditions of use. The following parameters can be changed: current limit and regulator parameters.

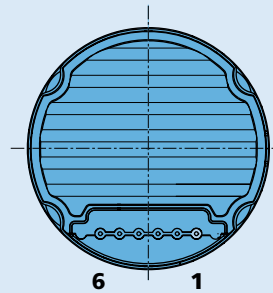
Circuit diagram / Connection information

Output circuit



* An additional external pull-up resistor can be added to improve the rise time.
Caution: I_{OUT} max. 15 mA must not be exceeded!

Cable connection



Connection

No.	Function
1	U _p
2	U _{mot}
3	GND
4	Unsol
5	DIR
6	FG

Caution:

Incorrect lead connection will damage the motor electronics!

Options

- Connector variant (Option no.: 3809)
 AWG 24 / PVC ribbon cable with connector Micro-Fit



- Analog Hall sensors (Option no.: 3692)

Accessories

- Programming board (Part No.: 6501.00088)

Full product description

- Example:
3268G024BX4 SC